Mask Set Errata for Mask 0N96V

This report applies to mask 0N96V for these products:

Table 1. Errata and Information Summary

Erratum ID	Erratum Title
ERR011543	FlexCAN: Nominal Phase SJW incorrectly applied at CRC Delimiter
ERR050443	FlexCAN: Receive Message Buffers may have its CODE Field corrupted if the Receive FIFO function is used in Classical CAN mode (CAN 2.0 version B)
ERR011097	LPSPI: Command word not loaded correctly when TXMSK=1
ERR011089	LPSPI: In Continuous transfer mode with CPHA =1, WCF bit is not set for every word.
ERR010777	SCG: Corrupted status when the system clock is switching.
ERR011114	SMC: invalid data might be fetched while accessing Flash in VLP modes

Table 2. Revision History

Revision	Changes
07/Jan/2019	Initial revision
20/APR/2020	The following erratum was added.
	• ERR050443
	The following erratum was revised.
	• ERR011543



ERR011543: FlexCAN: Nominal Phase SJW incorrectly applied at CRC Delimiter

Description: During the reception of a CAN-FD frame when the Bit Rate Switch (BRS) is enabled, the Synchronization Jump Width (SJW) for the CRC Delimiter bit is incorrectly defined by the Nominal Phase SJW. The CAN specification stipulates that the CRC Delimiter bit should have a SJW set by the Data Phase SJW.

> When a resynchronization event is triggered for the CRC delimiter bit (recessive in correct operation), the sample point will be adjusted by an amount as defined by the Nominal Phase SJW rather than the specified Data Phase SJW. This may result in the incorrect detection of a dominant bit leading to a CAN error frame. However, as the CRC delimiter bit position will only apply the SJW upon the detection of an unexpected dominant bit on the CAN bus, an error frame is already likely. For the case the SJW is applied at the CRC delimiter and a recessive bit is not detected, the receiving node will issue an error frame.

> The CAN protocol is designed to handle resynchronization errors and hence the CAN bus will recover from the insertion of the incorrect SJW at the CRC delimiter. Upon detecting the error frame the transmitting node will re-transmit the frame.

The following FlexCAN configurations are not affected:

- Classical CAN frames (CAN 2.0B)
- CAN FD frames with bit rate switch disabled (BRS = 0)
- CAN FD frames with Nominal Phase SJW equal to Data Phase SJW
- CAN FD transmissions

Configuration for the FlexCAN:

- Nominal Phase SJW is configured by the Resync Jump Width bit in the CAN Control Register 1 (CAN CTRL1[RJW]) or by the Extended Resync Jump Width bit in the CAN Bit Timing Register (CAN CBT[ERJW])
- Data Phase SJW is configured by the Fast Resync Jump Width bit in the CAN FD Bit Timing Register (CAN FDCBT[FRJW])

Workaround: The robustness of the CAN protocol ensures that the receiver automatically recovers from the application of the incorrect SJW. The CAN protocol is designed to recover from resynchronization errors and hence any frame that is not correctly received will be re-sent by the transmitting node.

ERR050443: FlexCAN: Receive Message Buffers may have its CODE Field corrupted if the Receive FIFO function is used in Classical CAN mode (CAN 2.0 version B)

Description: If the CODE Field of a Receive Message Buffer is corrupted it may deactivate the Message Buffer, so it is unable to receive new messages. It may also turn a Receive Message Buffer into any type of Message Buffer as defined in the Message buffer structure section in the device documentation.

> The CODE Field of the FlexCAN Receive Message Buffers (MB) may get corrupted if the following sequence occurs.

- 1- A message is received and transferred to an MB (i.e. MBx)
- 2- A new message start being received (i.e. message1), SMB0 (Serial Message Buffer 0) receives the message1 intended for MBx

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- 3- Before SMB0 being moved to MBx, MBx is locked by software for more than 20 CAN bit times (time determines the probability of erratum to manifest), therefore SMB0 is NOT transferred to MBx, it remains with message1.
- 4- A subsequent incoming message (i.e. message2) is being loaded into SMB1 (as SMB0 is full) and is evaluated by the FlexCAN hardware as being for the FIFO.
- 5- During the message2, the MBx is unlocked. Then, the content of SMB0 is transferred to MBx and the CODE field is updated with an incorrect value.

In case a customer does use Rx FIFO only or dedicated MB only, (i.e. either Rx MB or Rx FIFO is used) the problem doesn't occur. In case a customer does use Flexible Data Rate CAN (CAN FD), the problem does not occur also. So bottom line the problem does only occur if the FlexCAN is programmed to receive in the FIFO and dedicated MB at the same application.

Workaround: This defect only applies if the Receive FIFO is used. This feature is enabled by RFEN bit in the Module Control Register (MCR[RFEN]). If the Rx FIFO is not used, the Receive Message Buffer CODE Field is not corrupted.

The defect does not occur if the Receive Message Buffer lock time is less than or equal to the time equivalent to 20 x CAN bit time.

After receiving the Interrupt Flag for the corresponding MB (BUFx bit on the IFLAGx register) set by the hardware, the recommended way for the CPU to service (read) the frame received in a mailbox is by the following procedure:

- 1. Read the Control and Status word of that mailbox.
- 2. Check if the BUSY bit (CODE[0]) is deasserted, indicating that the mailbox is not locked. Repeat step 1) while it is asserted.
- 3. Read the contents of the mailbox.
- 4. Clear the proper flag in the IFLAG register.
- 5. Read the Free Running Timer register (TIMER) to unlock the mailbox

In order to guarantee that this procedure occurs in less than 20 CAN bit times the MB receive handling process in software (step 1 to step 5 above) should be performed as a 'critical code section' (interrupts disabled before execution) and should ensure that the MB receive handling occurs in a deterministic number of cycles.

If the MB receive handling process can't be guaranteed in a time, less than or equal to 20 CAN bit times, Rx FIFO should not be used together with the receive Message Buffers in a Classical CAN application.

ERR011097: LPSPI: Command word not loaded correctly when TXMSK=1

Description: When the Transmit Command Register is written with TCR[TXMSK]=1 and the next write to the TX FIFO is another command, then the first command may not load correctly.

Workaround: When writing the Transmit Command Register with TCR[TXMSK]=1, wait for the TX FIFO to go empty (FSR[TXCOUNT] = 0) before writing another command to the Transmit Command Register.

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ERR011089: LPSPI: In Continuous transfer mode with CPHA =1, WCF bit is not set for every word.

Description: When Transmit Command Register is written with TCR[CONT]=1 and TCR[CPHA]=1, SR[WCF] bit flag is not set after data is transferred. Therefore polling for SR[WCF] flag to identify if data has been sent can cause MCU to be stuck.

Workaround: When using continuous transfer mode TCR[CONT]=1 and TCR[CPHA]=1, do not use SR[WCF] flag to determine if data has been sent, fill up instead transmit FIFO with the following data without waiting for SR[WCF] flag to be set.

ERR010777: SCG: Corrupted status when the system clock is switching.

Description: The SCG_RCCR[SCS] and SCG_HCCR[SCS] may have a corrupted status during the interval when the system clock is switching

Workaround: The SCS field should be read twice by the software to ensure the system clock switch has completed.

ERR011114: SMC: invalid data might be fetched while accessing Flash in VLP modes

Description: VLPR and VLPS Low power modes are documented to work at System Clock and Core Clock at 4 Mhz and the Bus Clock at 4 MHz and DMA enabled from or to Flash memory. However any simultaneous access from any master (Core or DMA) to Dflash and Pflash may get invalid data while being in VLP modes and System clock, Core Clock and Bus Clock are above 1 Mhz

Workaround: There are two workarounds:

1. Restrict software to use either only Pflash or only Dflash only at a time in VLP modes for all masters (CPU,DMA). When switching from Pflash only access to Dflash only access let current DMA transactions accessing flash to complete and jump to SRAM location, wait for 40 cycles for the ongoing accesses to complete on the current flash before accessing dflash.

When switching from dflash only accesses to pflash only accesses let the current DMA transactions accessing dflash to complete

and wait for 40 cycles for accesses to complete on the dflash before accessing the pflash.

2. If both Pflash and Dflash needs to be accessed simultaneously, the VLP modes must be run with System Clock, Core Clock and Bus Clock of 1 MHz.

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