

Mask Set Errata

9S12A256MSE1
3/2002

Mask Set Errata
MC9S12A256 8-Bit
Microcontroller Unit



Introduction

This errata provides information applicable to the 1K79X MCU mask set of the 9S12A256.

MCU Device Mask Set Identification

The mask set is identified by a four-character code consisting of a letter, two numerical digits, and a letter, for example F74A. Slight variations to the mask set identification code may result in an optional numerical digit preceding the standard four-character code, for example 0F74A.

MCU Device Date Codes

Device markings indicate the week of manufacture and the mask set used. The data is coded as four numerical digits where the first two digits indicate the year and the last two digits indicate the work week. The date code "9115" would indicate the 15th week of the year 1991.

MCU Device Part Number Prefixes

Some MCU samples and devices are marked with an SC, PC, ZC, or XC prefix. An SC, PC, or ZC prefix denotes special/custom device. An XC prefix denotes device is tested but is not fully characterized or qualified over the full range of normal manufacturing process variations. After full characterization and qualification, devices will be marked with the MC prefix (or SC for some custom parts).

Errata System Tracking Numbers

MUCTS00xxx is the tracking number for device errata. It can be used with the mask set and date code to identify a specific errata to a Motorola representative.

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RTI Flag Clearing Delay when Running on PLL Clock

If the system is running on the PLL Clock at frequencies greater than 10 times the incoming oscillator clock, a RTI flag clearing sequence initiated immediately prior to executing the WAIT instruction, with the SYSWAI=1 and the PLLWAI=0, may not completely clear the RTI interrupt flag circuitry. This will result in a premature RTI flag and interrupt, if enabled.

Workaround After clearing the RTI flag add a three OSC clock cycle delay prior to entering WAIT mode.

Switching from SCAN to Single Mode Corrupts Data Registers

Switching from SCAN mode conversions to SINGLE mode conversion will corrupt the data registers by shifting their values forward by a word. The problem occurs when clearing the SCAN bit in ATDCTL5 during a 8 cycle window when sm2_state[4:0] = 07 and nextState2[4:0] = 06. The end of conversion flag will get set and the register mux control will be incremented immediately (nextRegCnt) so that further single conversions are stored in the wrong register.

Workaround Use the same code with the addition of DISABLING the ATD by first clearing ADPU bit in the ATDCTL2 register, then clearing the SCAN bin in ATDCTL5 to switch to single conversion mode, and then re-enabling the ATD.

ATD Current Consumption in Low Power Modes

If any ATD module is enabled when the CPU encounters a stop instruction or the CPU encounters a wait instruction with the ATD stop in wait bit set, ATD current consumption may be out of specification.

Workaround The ATD modules should be disabled prior to entering stop mode.

RTI Clocks Remain Active if RTIF is Set

The RTI clock continues to run if the RTIF(RTI interrupt flag) is set, regardless of the RTICTL register setting or RTIWAI bit setting. This can lead to faulty operation in the following scenarios:

1. If WAIT mode is entered with the RTIWAI bit set, RTIE bit cleared, and the RTIF set, the RTI clock, and RTI counters will continue to operate in WAIT mode and consume current.
2. If The RTICTL register is cleared (RTICTL=0) while the RTIF is set, the RTI clocks will continue to run until the RTIF is cleared.
3. If a new non-zero value is written to the RTICTL register when the RTIF is set, the first RTI time-out period following the write may not be the correct duration.

Workaround

Clear the RTICTL register and then RTIF prior to entering WAIT mode or before writing a new non zero value to the RTICTL register.

SPI Locks if Disabled During Message Transmission

In master mode during a transmission SPI locks if SPE bit is cleared. After re-enabling, writing to SPIDR does not result in message transmission.

Workaround

Disable the SPI module only if transmission queue is empty (SPTEF=1) and transfer is complete (SPIF=1).

Self Clock Frequency Too High

The self clock mode frequency can exceed the maximum specified value. In this case the clock quality check will always fail for EXTAL frequencies below 800kHz. This affects two additional spec values.

1. The clock quality check may fail for EXTAL frequencies below 800kHz. Therefore the crystal oscillator frequency range minimum value is 1.0MHz.
2. The PLL may not lock to the minimum specified PLL frequency of 8.0MHz. Therefore the VCO locking range minimum value is 12.0MHz, which corresponds to a 6.0MHz bus frequency.

Workaround

1. Instead of 500kHz use a 1MHz quartz, resonator or oscillator.
2. Only synthesize PLL frequencies from 12MHz to the maximum specified value. 12MHz PLL frequency corresponds to 6MHz bus frequency.

BDM Loses Sync when Using PLL at High Frequencies

When using the BDM constant clock source, i.e. CLKSW=0, with the PLL engaged, PLLSEL=1, and the PLL multiplier greater than or equal to 2, the BDM can lose communication with the host system.

Workaround Do not use the BDM constant clock source with the PLL engaged and a multiplier greater than or equal to 2. Set CLKSW=1 before engaging the PLL.

Clock Monitor Frequency Lower Than Specified

The clock monitor failure assert frequency is f_{CMFA} (max:100kHz, typ:50kHz, min:25kHz) and not as the specified f_{CMFA} (max:200kHz, typ:100kHz, min:50kHz).

Workaround None

PWM Channel Early Start After Leaving Emergency Shutdown Mode

When recovering from the emergency shutdown mode by disasserting the active level on the PWM emergency shutdown input pin and subsequently asserting the PWMRSTRT bit, the enabled PWM channels do not hold the shutdown output level (PWMLVL) until the corresponding counter passes zero. This may result in a pulse of undefined length on enabled PWM channels.

Workaround None

Breakpoint Module: Potential Extraneous Data Match

When using the breakpoint in full mode with the read/write match function disabled, there is a chance of a false match. Internally there is a separate read data bus and write data bus. When in full mode with the read/write match function is disabled, both buses are always compared to the contents of data match register. The circuit should only match the active bus on any particular bus cycle. The false match can occur if the address matches on a read cycle and matching data is on the write data bus or the address matches on a write cycle and the matching data is on the read data bus.

Workaround When using full mode, always enable the read/write match and select the appropriate state of read/write. This will avoid false matches.

SPI Can Receive Incorrect Data in Slave Mode

An SPI configured for slave mode operation can receive incorrect data. If there are clock edges on SCK while SPE=0, and then SPE is set to one, the received data will be incorrect. In CPHA=1 mode the SPI will continue to receive incorrect data as long as SPE=1.

Workaround

Depending on the current mode on SPI, the following bits have to be configured while disabling the SPI:

- Set CPHA=1 and make sure that the CPOL-bit is clear every time the SPI is disabled from slave mode.
- Clear CPHA and make sure that CPOL is clear as well every time the SPI is disabled from master mode.

SPIF Flag is Set Wrong in Slave Mode after SPI Re-enabling

The SPIF-flag is set wrong under the following conditions:

- Receiving a byte with the SPI while configured as slave, CPHA=1 and CPOL=1
- Clearing SPIF in SPISR normally (read SPISR followed by a read of SPIDR)
- Disabling the SPI through clearing SPICR1
- Re-enabling the SPI (with CPHA=1 and CPOL=1)

Three bus cycles after this sequence SPIF in SPISR is set, which is not correct.

Workaround

A sequence to clear the wrong SPIF is:

If no other IRQs enabled:

- Insert a short delay (min. 3 bus cycles) after re-enabling the SPI and clear the SPIF by reading the SPISR followed by SPIDR after re-enabling the SPI.

If other IRQs enabled (excluding X-IRQ):

- Before re-enabling the SPI, disable all IRQs through a set of bit CCR[4] (IRQ mask) using the instruction SEI
- Re-enable SPI, insert a short delay (min. 3 bus cycles) after SPI re-enabling
- Clear SPIF by a read access to the SPISR followed by SPIDR.
- Re-enable all IRQs through clearing bit CCR[4] using the instruction CLI

In the case where a hardware interrupt is used, it is possible to lose an SPI IRQ.

SPI Locks if Re-enabled as Master

The SPI locks if it is disabled in master mode with CPHA=1 in SPICR1 and re-enabled in master mode with CPHA=1.

Workaround

Make sure that CHPA is not set when SPI is disabled after a transmission in master mode.

ATD: Incorrect Offset of Transfer Curve for 8-Bit Resolution

8-bit mode transfer characteristic shows incorrect result of 17.5mV for first transition. This is because independently of 8- or 10-bit resolution an offset of 2.5mV is used (which is only correct for 10-bit resolution).

Workaround

None

Non-Multiplexed Addresses on PK Change Before End of Cycle

In expanded modes with the EMK emulate port k bit set and the EXSTR[1:0] external access stretch bits 1 & 0 set to 01, 10 or 11 the non-multiplexed addresses on PK[5:0] change during E clock high phase at t4.

Workaround

If the external access is stretched (EXSTR[1:0] set to 01, 10 or 11) off chip address latches should be used to register the non-multiplexed addresses on PK[5:0].

SCI Interrupt Asserts Only if an Odd Number of Interrupts Active

The interrupt of the SCI is only asserted if an odd number of interrupts is active (i.e. flags set and enabled). Example: If an Transmit data register empty and an receive ready interrupt are active at the same time the interrupt request to the CPU is not asserted. This can lead to missing interrupts or spurious interrupts i.e. the request gets deasserted before the CPU fetches the interrupt vector. Those spurious interrupts will execute on the SWI vector. The interrupt flag setting is always correct.

Workaround

There is no general workaround. Some typical cases will be described. The problem is reduced by fast interrupt response times and slow baud rates.

1. Single wire interfaces as used in the automotive industry Since the transmit and receive process are linked to each other a mix of interrupt handling and polling is possible. Here several scenarios are possible to come to a stable operation but each might require a rewriting of the lower level drivers. The easiest one is to use only receive interrupt and fill the first two bytes of a message into the transmit queue by polling. With each byte received the transmit data buffer is empty and a new byte can be queued.
2. Full duplex operation If the SCI interrupt is not asserted while e.g. a transmit or receive interrupt are pending the received byte will cause an overflow error (3rd interrupt) and this will then assert the interrupt. A software can detect the overrun error and request a re-transmission of the last message frame. One byte is lost here. Polling flag bits at a frequency of one byte time (e.g., 1 ms for 9600 baud) Toggling one of the enable flags at the frequency of one byte.

5 Volt Only Device (Voltage Regulator On)

Using the microcontroller with an external voltage supply ($V_{\text{REGEN}} = 0$) at the minimum digital logic supply voltage $V_{\text{DD}1/2} = 2.25\text{V}$ may cause problems due to voltage drop on bond wires/lead frame or on power network.

Workaround

The internal voltage regulator should always be enabled ($V_{\text{REGEN}}=1$).

SPIF Flag is Set Wrong in Slave Mode

If the SPI is enabled in slave mode with the SS and SCK pins driven low and all other bits in their reset state, three bus clock cycles after clearing the CPHA bit, the SPIF flag is set.

Workaround Change of CPHA bit should only occur while SPI is disabled (SPE bit cleared).

SPIF Flag is Set Wrong — SPI Locks in Master Mode

The SPIF flag is set wrongly after the following sequence:

1. SPI receives a byte in slave mode
SPIF flag is cleared normally (read SPISR, read SPIDR)
2. SPI is disabled through the following sequence
(given by workaround for MUCts00470 and MUCts00479)
SPICR1 is set to 0x04h
3. SPI is re-enabled as master through the following sequence
(given by workaround for MUCts00470 and MUCts00479)
SPICR1 is set to 0x08h, SPICR1 is set to 0x54h
Three bus cycles after SPICR1 was set to 0x08h, the SPIF flag is set wrongly and also the master locks

Workaround

1. SPI receives a byte in slave mode
SPIF flag is cleared normally (read SPISR, read SPIDR)
2. Disable SPI through the following sequence
(given by workaround for MUCts00470 and MUCts00479)
Set SPICR1 to 0x04h
3. Re-enable SPI as master through the following sequence
(given by workaround for MUCts00470 and MUCts00479)
Set SPICR1 to 0x0Ch (actual workaround for MUCts00548)
Set SPICR1 to 0x08h
Set SPICR1 to 0x54h

Missing External ECLK During Reset Vector Fetch

The reset conditions of the ECLK control logic in the MEBI inhibit the generation of 1 ECLK pulse during the reset vector fetch. This can prevent the external logic from latching the reset vector address.

Workaround None

SPIDR is Writable though the SPTEF Flag is Cleared

Data can be placed into the SPI Data Register (SPIDR) though the SPTEF flag is cleared. The SPTEF flag indicates, if the transmit buffer is empty (SPTEF=1) or full (SPTEF=0). Data can be placed into the SPI Data Register by reading SPISR with SPTEF=1 followed by a write to the SPI Data Register. If SPTEF=0, a write to the SPI Data Register should be ignored, according to the SPI specification. This is not true for the current implementation, where data can be placed into the SPI Data Register though SPTEF=0.

Workaround Do not write to the SPI Data Register until you have read SPISR with SPTEF=1.

Erase Verify Impact on Subsequent Erase Operations

If the Erase Verify (\$05) command is issued on an array that is not erased as indicated by the FSTAT/ESTAT BLANK bit not being set upon command completion, the execution of the Sector Erase (\$40) or Mass Erase (\$41) command will not properly erase the intended region. The Program (\$20) command will execute properly.

Workaround If the Erase Verify (\$05) command is issued on an array that is not erased, subsequent Sector Erase (\$40) or Mass Erase (\$41) commands must be issued twice before the intended region is properly erased.

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