

Motor Application Tuning Wizard

Customize motor control applications to your PMSM

Overview

Current trends in motor control application development are increasing motor drive efficiency, decreasing cost and speeding up time to market. The way to accomplish demanding requirements is an implementation of state-of-the-art motor control algorithms and use of motors capable to be driven with high efficiency.

Freescale offers such solutions with sensorless control of permanent magnet synchronous motors (PMSM). The sensorless algorithm implementation decreases total cost eliminating a rotor position sensor.

Instead of the position sensor, the sensorless algorithm estimates rotor position by calculating a state observer in real time. Such complex routines require precise settings of motor model parameters.

To simplify process of control algorithm parameter calculations, setting and tuning, the Tuning Wizard tool was developed.

Features

The Tuning Wizard is an HMTL-based user-friendly graphical plug-in tool for FreeMASTER. The tool can be used for PMSM field-oriented control application development and real-time parameter tuning and helps motor control users to adapt Freescale motor control applications to their motors without detailed knowledge of source code and control constant calculations.

Tuning Wizard Key Features

- Static calculation of control parameters
- Real-time tuning of selected control structures
- Storing output constants in header file
- Configurable IDE

Figure 1: Tuning Wizard Control Structure Page

Motor 1:			Motor 2:			•	Motor 3:		
Introduction	Parameters	Current Loop	Speed Loop	Sensorless	Output File	Cascade	App Control		
		,	Application	Control S	Structure	•			
T State Co	ontrol	1 F C	ascade Contro	I Structure C	omposition				
	ON		Scalar Control	1		Um		M	
			view	Į, DISA	IDLED	Frequency		[Hz]	
	0	ve	oltage FOC Cont	rol jo		Ud_req		M	
	OFF		view	DISA	ABLED	Uq_req		M	
Ap	plication Stat	ie o	urrent FOC Cont	and a second		ld rea		[4]	
	READY		view	DIS	ABLED	Id_red		(A)	
	Lindata EDM		peed FOC Contr	rol		Speed reg	1500	[rpm]	
	opourorrow		view	ENA	BLED	ld = manual 💌	0	[A]	
			Position & Spee Feedback	d ENA	BLED	Sensor type	sensorless -	-	

- Up to three PMSMs support
- Fractional 16-, 32-bit and floating number format selector
- Online update of selected
 application control variables

To run new PMSM using Freescale application code, the input parameters are required to be added into the Tuning Wizard. The parameters are used for calculations of state observer, control loop PI controller and application dependent constants. Required parameters can be taken from the motor data sheet or using a Freescale procedure for PMSM parameter measurement.

The Tuning Wizard plug-in tool consists of several dedicated control tabs. The tab configuration depends on an application type (sensor or sensorless). Available control tabs are:

- 1. Introduction: Basic application description
- 2. **Parameters:** Obligatory input motor and application parameters
- 3. **Current loop:** Inner control loop, PI controller (parallel or recurrent form) of d,q currents
- 4. **Speed loop:** Outer loop, Pl controller (parallel or recurrent form), speed ramp and filter

- 5. **Position and speed:** Sensor selector (quadrature encoder, Hall sensors, SinCos, resolver)
- 6. **Sensorless:** BEMF DQ observer, tracking observer
- 7. **Output file:** List of constants generated to output header file in required target format
- 8. **Cascade:** Application tuning based on cascade control structure (scalar, voltage FOC, current FOC, speed FOC, field weakening)
- 9. App control: FreeMASTER userdefined control page

Freescale Enablement

The Tuning Wizard tool will be delivered as part of the PMSM reference designs to enable users an adaptation of Freescale motor control applications.

Prepared application notes will explain the Tuning Wizard concept from the structure and feature point of view and also how to integrate the plug-in tool to existing motor control applications.

Application notes and other information about the Tuning Wizard tool are available at

freescale.com/motorcontrol.

How to Reach Us:

Home Page:

freescale.com

Motor Control Portfolio Information:

freescale.com/motorcontrol

e-mail: support@freescale.com

USA/Europe or Locations Not Listed:

Freescale Semiconductor Technical Information Center, CH370 1300 N. Alma School Road Chandler, Arizona 85224 1-800-521-6274 480-768-2130 support@freescale.com

Europe, Middle East, and Africa:

Freescale Halbleiter Deutschland GmbH Technical Information Center Schatzbogen 7 81829 Muenchen, Germany +44 1296 380 456 (English) +46 8 52200080 (English) +49 89 92103 559 (German) +33 1 69 35 48 48 (French) support@freescale.com

Japan:

Freescale Semiconductor Japan Ltd. Headquarters ARCO Tower 15F 1-8-1, Shimo-Meguro, Meguro-ku, Tokyo 153-0064, Japan 0120 191014 +81 3 5437 9125 support.japan@freescale.com

Asia/Pacific:

Freescale Semiconductor Hong Kong Ltd. Technical Information Center 2 Dai King Street Tai Po Industrial Estate, Tai Po, N.T., Hong Kong +800 2666 8080 support.asia@freescale.com Information in this document is provided solely to enable system and software implementers to use Freescale Semiconductor products. There are no express or implied copyright license granted hereunder to design or fabricate any integrated circuits or integrated circuits based on the information in this document.

Freescale Semiconductor reserves the right to make changes without further notice to any products herein. Freescale Semiconductor makes no warranty, representation or guarantee regarding the suitability of its products for any particular purpose, nor does Freescale Semiconductor assume any liability arising out of the application or use of any product or circuit, and specifically disclaims any and all liability, including without limitation consequential or incidental damages. "Typical" parameters which may be provided in Freescale Semiconductor data sheets and/or specifications can and do vary in different applications and actual performance may vary over time. All operating parameters, including "Typicals" must be validated for each customer application by customer's technical experts. Freescale Semiconductor does not convey any license under its patent rights nor the rights of others. Freescale Semiconductor products are not designed, intended, or authorized for use as components in systems intended for surgical implant into the body, or other applications intended to support or sustain life, or for any other application in which the failure of the Freescale Semiconductor product could create a situation where personal injury or death may occur. Should Buyer purchase or use Freescale Semiconductor products for any such unintended or unauthorized application, Buyer shall indemnify and hold Freescale Semiconductor and its officers, employees, subsidiaries, affiliates, and distributors harmless against all claims, costs, damages, and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death associated with such unintended or unauthorized use, even if such claim alleges that Freescale Semiconductor was negligent regarding the design or manufacture of the part.

freescale

For more information, visit freescale.com/motorcontrol

Freescale and the Freescale logo are trademarks of Freescale Semiconductor, Inc., Reg. U.S. Pat. & Tm. Off. All other product or service names are the property of their respective owners. © 2012 Freescale Semiconductor, Inc.

Document Number: BBTNGWZRDART REV 0