

AN14680

Debugging Kernel Space Using GDB and KGDB

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Application note

Document information

Information	Content
Keywords	AN14680, Kernel GNU Debugger, i.MX 8M, Ubuntu 22.04
Abstract	This document provides a step-by-step guide for setting up Kernel GNU Debugger (KGDB) on a development board (target).



1 Introduction

This document provides a step-by-step guide for setting up GNU Debugger (GDB) on a Linux machine (host). GDB is a powerful debugging tool for programs written in various programming languages, including C and C+. The host further connects to Kernel GNU Debugger (KGDB) on a development board (target).

KGDB is an extension of GDB designed specifically for debugging the Linux kernel, including device drivers and kernel modules. This document includes instructions on configuring the kernel, sharing the serial port, and establishing a debugging session.

2 Prerequisites

Following are the prerequisites for the setup:

- NXP development board (target)
- Linux host machine with the appropriate cross-compile toolchain for the target
- Serial connection between the host and target

Set up the development board that is being debugged with KGDB (target) and a Linux machine with GDB (host). Connect the target to a serial console with host. Install the cross-compiled toolchain for your target, which includes the GDB, on the host.

This document has been tested on the following setup:

- Host machine: Running Ubuntu 22.04
- Target device: NXP i.MX 8M Plus Evaluation Kit (imx-8mp-evk) with BSP and toolchain version 6.6.3-1.0.0

3 Setting up serial port sharing with kdmx

Kdmx is a tool used along with KGDB which multiplexes connections. This tool allows both standard serial console and debugging session to share the serial port.

The KGDB requires a dedicated serial connection. Also, a console is needed for the system interaction. Since the board has only one serial port, the kdmx tool is used to multiplex the serial port to satisfy these requirements.

3.1 Install kdmx

Run the following commands on the host to install kdmx.

```
$ git clone https://kernel.googlesource.com/pub/scm/utils/kernel/kgdb/agent-proxy
$ cd agent-proxy/kdmx/
$ make
$ gcc -Wall -Wunreachable-code -D_XOPEN_SOURCE -c -o kdmx.o kdmx.c
$ gcc -o kdmx kdmx.o
```

3.2 Run kdmx

To share the serial port, execute the following command:

```
./kdmx -p /dev/ttyUSB<X> -b 115200
```

X is the port number for the serial console.

4 Configure and compile the kernel with KGDB support

This section explains the procedure to complete the KGDB installation.

4.1 Enable kernel configuration

Reconfigure and recompile the kernel with the following options:

- Enable the following configurations in the `.config` file:

```
CONFIG_KGDB=y
CONFIG_KGDB_SERIAL_CONSOLE=y
CONFIG_MAGIC_SYSRQ=y
CONFIG_DEBUG_INFO=y
CONFIG_FRAME_POINTER=y
```

- Disable the following configurations in the `.config` file:

```
CONFIG_DEBUG_INFO_REDUCED
CONFIG_RANDOMIZE_BASE
```

To build the kernel, refer to “How to build U-Boot and kernel in a standalone environment” of the *i.MX Linux User Guide* (document [UG10163](#)).

4.2 Verify debug symbols

Ensure the compiled vmlinux binary contains the debugging symbols by running the command given below:

```
$ file vmlinux
```

The expected output of running the above command is as below:

```
vmlinux: ELF 64-bit LSB pie executable, ARM aarch64, version 1 (SYSV),
statically linked, BuildID[sha1]=2e57df8b4e05509036e463d820f9cc4d87304061, with
debug_info, not stripped
```

Remember to search for ‘with debug_info, not stripped’ message.

4.3 Compile and flash the kernel

After compiling the kernel with debugging symbols, flash the kernel image to the target device. The kernel image is created in `<build_folder>/arch/arm64/boot/Image`. Copy and overwrite the image on the bootpartition of the SD card.

4.4 Verify KGDB installation

Check if KGDB is available on the target by running the command given below:

```
$ ls /sys/module/kgdboc/
```

The expected output is `parameters uevent`.

5 Entering debug mode on the target

You can enter the KGDB debugging mode either at boot time or during runtime. The following sections explain both scenarios.

5.1 Entering debug mode at boot time

To enable KGDB, it is necessary to modify the U-Boot environment variables. Steps for this process are given below:

1. Enter U-Boot and modify the boot arguments as below:

```
u-boot=> editenv mmcargs
```

Add `kgdboc=${console} kgdbwait` at the beginning of the arguments.

```
u-boot=> printenv mmcargs
mmcargs=setenv bootargs kgdboc=${console} kgdbwait ${jh_clk} ${mcore_clk}
console=${console} root=${mmicroot}
u-boot=> boot
```

2. The system pauses during boot. It displays the output as below:

```
[1.458834] KGDB: Registered I/O driver kgdboc
[1.463339] KGDB: Waiting for connection from remote gdb...
```

3. Now, the kernel is in debug mode. Proceed to connect GDB from the host.

5.2 Entering debug mode at runtime

To start KGDB while the system is running, follow the steps as given below:

1. Set the serial port for debugging.

```
$ echo <tty> > /sys/module/kgdboc/parameters/kgdboc
```

tty is the serial console for the target, which can be seen after the board boot in the first line as below:

```
NXP i.MX Release Distro 6.6-nanbiel imx8mp-lpddr4-evk ttymxc1
imx8mp-lpddr4-evk login:
```

2. Trigger KGDB as below:

```
$ echo g > /proc/sysrq-trigger
```

3. Now, the kernel freezes and displays the below message:

```
[28.710921] KGDB: Entering KGDB
```

4. The kernel is now in debug mode. Proceed to connect GDB from the host.

6 Connecting to KGDB from the host

Once the target is in debugging mode, connect to KGDB using GDB from the host. Follow the steps for this process as below:

1. Switch to the root user.

```
$ sudo su
```

2. Load the toolchain environment.

```
$ source /path/to/environment/toolchain
```

3. Launch GDB for vmlinux.

```
$ aarch64-poky-linux-gdb vmlinux
```

4. Inside GDB, configure the serial connection and connect to the target.

```
(gdb) set serial baud 115200
(gdb) target remote /dev/pts/X
```

X is the number for the GDB connection from kdmx.

Once connected, begin the debugging.

7 Debug a kernel module

To debug an external kernel module, you can either debug an already probed module or debug it during the probing process. The probing process is also referred to as the initialization function of the module.

Ensure that the module is compiled with debug flags. After compilation, copy the module to the Linux build folder of the host machine. For this example, use the module 'test.ko'.

7.1 Debug an already loaded kernel module

1. Load the module on the target with the command as given below:

```
$ modprobe test
```

2. Retrieve the address of the section namely '.text', '.data', and '.bss' (optional).

```
$ cd /sys/module/test/sections/
$ cat .text .data .bss
```

Example output is as below:

```
0xffff80007a376000 - .text
0xffff80007a38c360 - .data
0xffff80007a38cf00 - .bss
```

3. Enter the debug mode on target (Refer to [Section 5.2](#)).
4. Connect to KGDB from the host machine (Refer to [Section 6](#)).
5. Add module addresses to the GDB with the command as given below:

```
(gdb) add-symbol-file <path-to-module> <address of module's .text section> \
-s .data <address of module's .data section> \
-s .bss <address of module's .bss section>
```

For the test module, the command is given below.

```
(gdb) add-symbol-file test.ko 0xffff80007a376000 \
-s .data 0xffff80007a38c360 \
-s .bss 0xffff80007a38c360
```

6. Set breakpoints anywhere in the module sources and start the debugging process.

7.2 Debug a kernel module during loading

1. Connect to the target machine (Refer to [Section 6](#)).

2. Locate the **load_module()** function in 'kernel/module/main.c' and identify the following lines:

```
2925 /*
2926 * Now we've got everything in the final locations, we can
2927 * find optional sections.
2928 */
2929 err = find_module_sections(mod, info);
2930 if (err)
2931     goto free_unload;
```

3. Set a breakpoint at `if (err)` (line 2930 for linux-imx lf-6.12.y), referred to as breakpoint 1.

```
(gdb) breakpoint kernel/module/main.c:2930
(gdb) continue
```

4. The target unfreezes. Load the module on it as below:

```
# insmod <path-to-module>
```

5. The GDB stops at breakpoint 1 as can be seen below:

```
Thread 186 hit Breakpoint 1, load_module (info=info@entry=0xffff80000adfbdb30,
uargs=uargs@entry=0xaaaaaab8ede0 "", flags=flags@entry=0) at kernel/module/
main.c:2803
2803         if (err < 0)
```

6. Retrieve the module sections addresses with the command as given below:

```
(gdb) print mod->init_layout.base (.init.text section address)
0xffff800001345000
(gdb) print mod->core_layout.base (.text section address)
0xffff800001340000
```

7. Add addresses to the GDB as below:

```
(gdb) add-symbol-file test.ko -s .init.text 0xffff800001345000 -s .text
0xffff800001340000
```

8. Set a breakpoint in the initialization function of the module as below:

```
(gdb) breakpoint custom_init
```

9. Delete the first breakpoint as below. This step prevents the repeated GDB stops.

```
(gdb) delete breakpoint 1
(gdb) continue
```

10. The GDB stops at the second breakpoint, entering the initialization function of the module.

8 Note about the source code in the document

Example code shown in this document has the following copyright and GPL-2.0-only license:

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9 Revision history

[Table 1](#) summarizes revisions to this document.

Table 1. Revision history

Document ID	Release date	Description
AN14680 v.1.0	16 May 2025	<ul style="list-style-type: none">Initial public release

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