AN13507

How to Perform Boundary Scan for LPC55(S)xx based on μ Trace and Trace32 Rev. 1 — 14 November 2023 Application note

Document information

Information	Content
Keywords	AN13507, boundary scan, Boundary-Scan Description Language (BSDL)
Abstract	This application note describes how to enter the boundary scan mode, how to perform boundary scan test based on Boundary-Scan Description Language (BSDL) on LPC55(S)xx series, an overview of JTAG and boundary scan technology.



How to Perform Boundary Scan for LPC55(S)xx based on µTrace and Trace32

1 Overview

LPC55(S)xx is a microcontroller based on the Arm Cortex-M33 for embedded applications. It supports JTAG boundary scan. This document describes:

- · How to enter the boundary scan mode.
- How to perform a boundary scan test based on Boundary-Scan Description Language (BSDL) on LPC55(S)xx series.
- · An overview of JTAG and boundary scan technology.

To understand this document better, basic knowledge of JTAG and boundary scan is required.

2 JTAG and boundary scan

2.1 Introduction

JTAG/boundary scan is an interface containing four ports. The interface allows access to the special embedded logic on most chips. JTAG/boundary can provide several functions that can contain any or all the following:

- Probe-less device connectivity test.
- · Logic programming for Flash memory, CPLD, and FPGA.
- Debug logic in microprocessors and microcontrollers used for software debugging, or test connections with peripheral devices at speed without embedded software.

2.2 Development history

The architecture for Test Access Port (TAP) and Boundary Scan is defined in IEEE Std 1149.1. The development history of this standard is summarized as follows:

- 1985 Joint European Test Action Group (JETAG) was formed.
- 1986 Joint European Test Action Group (JETAG) was renamed as Joint Test Action Group (JTAG).
- 1986-1988 JTAG Technical Subcommittee developed and published a series of proposals for a standardized form of boundary scan.
- 1988 the last of these proposals, JTAG Version 2.0, was offered to the IEEE Testability Bus Standards
 Committee (P1149) and was accepted by P1149. JTAG proposal became the basis of a standard within the
 Testability Bus family.
- 1990 From 1990, JTAG developed a supplement for correction, clarification, and enhancement.
- 1993 IEEE Std 1149.1aTM-1993
- 1994 IEEE Std 1149.1b-1994
- 2001 IEEE Std 1149.1-2001
- 2013 IEEE Std 1149.1-2013

2.3 Basic principle

Boundary scan is a method for testing interconnects on PCBs and internal IC subblocks. For boundary scan tests, more logic is added to the device. Boundary scan cells are placed between the core logic and the ports.

In the boundary scan test, each primary input and output signal on a device is supplemented with a multipurpose memory element called as a boundary scan cell. These cells are connected to a shift register, which is referred to as the boundary scan register. This register can be used to read and write port states.

In normal mode, these cells are transparent and the core is connected to those ports. In the boundary scan mode, the core is isolated from the ports and the JTAG interface controls the port signals.

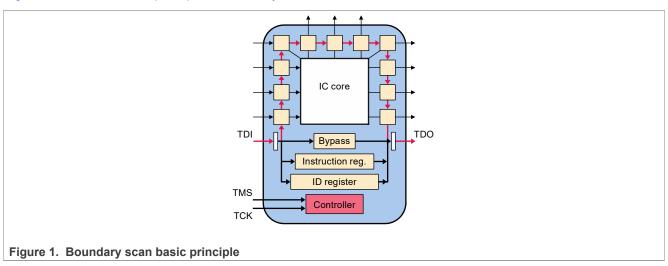
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Figure 1 shows the basic principle of boundary scan.



2.4 Instruction set

Table 1 describes the boundary scan instructions defined in the IEEE Std 1149.1.

Table 1. Standard instruction set

Instruction	Mandatory/Optional	Description
BYPASS	Mandatory	TDI is connected to TDO via a single shift register.
SAMPLE	Mandatory	Takes a snapshot of the normal operation of the Integrated Circuit (IC).
PRELOAD	Mandatory	Loads data to the boundary scan register.
EXTEST	Mandatory	Applying preloaded data of the boundary scan register to the ports.
INTEST	Optional	Applying the preloaded data of the boundary scan register to the core logic.
RUNBIST	Optional	Executing a self-contained self-test of the IC.
CLAMP	Optional	Applying the preloaded data of the boundary scan register to the ports and selects the bypass register as the serial path between TDI and TDO.
IDCODE	Optional	Reading the device identification register.
USERCODE	Optional	Reading and writing a user programmable identification register.
HIGHZ	Optional	Placing the IC in an inactive drive state (for example, all ports are set to high-impedance state).

2.5 JTAG Test Access Port (TAP)

TAP is a general-purpose port that can provide access to many test support functions built into a component, including the test logic. It is composed of **a minimum of the three input connections**, which are **TCK**, **TMS**, **TDI**, and **one output connection**, which is **TDO**. An optional fourth input connection, TRST, is provided for asynchronous initialization of the test logic.

Table 2 describes TAP signals.

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Table 2. TAP signal description

Signal name	I/O type	Description
TCK	Input	Providing the clock for the test logic.
TMS	Input	Value of the signal presented as TMS at the time of a rising edge at TCK determines the next state of the TAP controller. The circuit that controls test operations.
TDI	Input	Serial test instructions and data received by the test logic at TDI.
TDO	Output	Serial output for test instructions and data from the test logic.
TRST	Input	Provided for asynchronous initialization and active low.

Note: JTAG is used on LPC55(S)xx devices for boundary scan and the production test only. It cannot be used for debugging purposes.

2.6 BSDL

Boundary-Scan Description Language (BSDL) is based on the syntax and grammar of Very high-speed integrated-circuit Hardware Description Language (VHDL). BSDL is not a general-purpose hardware description language. It describes key aspects to implement the boundary scan within a particular component.

Table 3 lists elements contained in the BSDL file.

Table 3. BSDL elements

Element	Description
Entity Description	Statement for device name or functionality.
Generic Parameter	Description for package or pin mapping.
Logical Port Description	Description for pin types such as in, out, in-out, linkage.
Standard Use Statement	References external definitions.
Component Conformance Statement	Standards to follow.
Device Package Pin Mapping	Description for pin mapping.
Scan Port Identification	Pin description on device for JTAG TAP including TCK, TMS, TDI, and TDO.
Compliance Enable Description	Pins involved in entering boundary scan mode and level applied to the pins. It is useful for chip enter boundary scan mode.
Instruction Register Description	Instruction length and instruction code. Sometimes it includes device-specific instruction, also called as private instruction.
Register Access Description	Registers corresponding to specific instructions
Boundary-Scan Register Description	List recording the boundary scan cells and functionality of these boundary scan cells.

Download BSDL files for LPC55(S)xx through the following links:

- LPC55(S)6x: https://www.nxp.com/downloads/en/bsdl/LPC55S6X-BSDL.zip
- LPC55(S)2x: https://www.nxp.com/downloads/en/bsdl/LPC55S2X-BSDL.zip
- LPC55(S)1x: https://www.nxp.com/downloads/en/bsdl/LPC55S1X-BSDL.zip

For the latest BSDL file of a specific part, download it from <u>NXP official website</u>. Taking the BSDL file for LPC55(S)6x as an example, perform the following steps:

• Go to NXP official website and type the product model in the search box. In this example, it is LPC55S69.

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- To go to the homepage of the corresponding part, click the specific part in the search result list. In this example, it is **LPC55S69JBD100**.
- To go to the TOOLS&SOFTWARE tab on the Introduction page of the desired part, click the Tools and Software quick link.
- Download BSDL file from an item named **Design Tools and Files** in the **Tools and Software** section.

2.7 More information on JTAG and boundary scan

For more information on JTAG and boundary scan, see the links below:

- Homepage for JTAG and boundary scan: https://www.jtag.com/
- IEEE Std 1149.1
 - version 1990: https://standards.ieee.org/standard/1149 1-1990.html
 - version 2001: https://standards.ieee.org/standard/1149 1-2001.html
 - version 2013: https://standards.ieee.org/standard/1149 1-2013.html

3 Building boundary scan test environment

3.1 Introduction to boundary scan test tool suite

In this application note, the boundary scan test uses the tool set from Lauterbach, which is all-in-one debug and trace solution for Cortex-M. This tool set includes the following two parts:

µTrace for Cortex-M

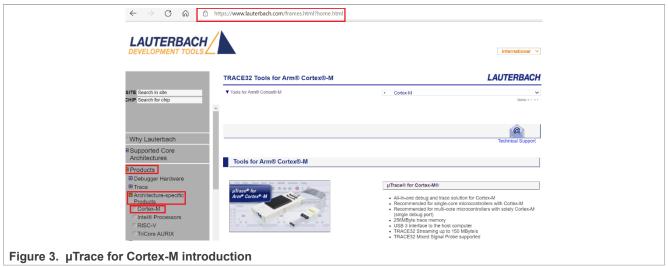
μTrace for Cortex-M is one of the architecture-specific products from Lauterbach. The features are as below:

- On-chip/external flash programming, debug, trace, and JTAG boundary scan
- Recommended for single-core microcontrollers with Cortex-M
- Recommended for multicore microcontrollers with solely Cortex-M (single debug port)
- 256 MBytes trace memory
- USB 3 interface to the host computer
- TRACE32 streaming up to 150 MBytes/s
- TRACE32 mixed signal probe supported



For more information about µTrace for Cortex-M, see Figure 3.

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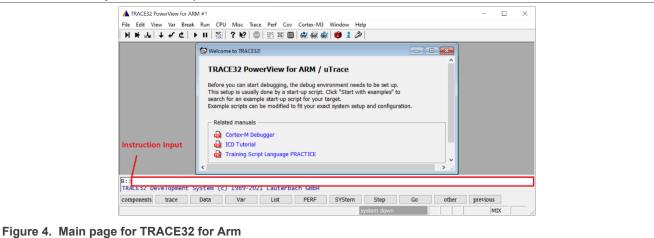


• TRACE32

TRACE32 is a simulation test tool developed by Lauterbach. It runs on a personal computer. It is used with μ Trace for Cortex-M for on-chip/external Flash programming, debugging, tracing, and JTAG boundary scan. It supports various processor architectures, including standard processors such as **Arm**, MIPS, PowerPC and DSP, soft cores, and coprocessors.

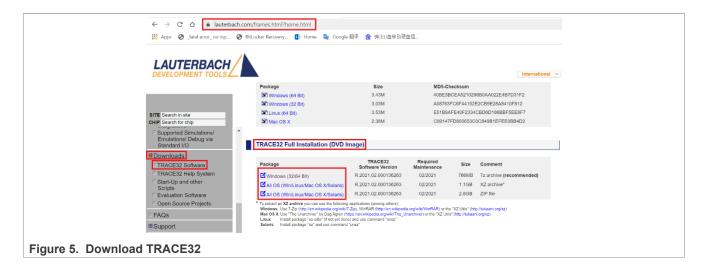
For boundary scan, TRACE32 provides GUI operations for interactive test and supports a script for automated test. To execute many commands, such as, system settings, JTAG, and BSDL, make a script contain these commands. To complete the test, execute the script. The execution is efficient and reduces the possibility of errors in the command-line mode.

TRACE32 supports command-line input. The command-line input is at the bottom of the TRACE32 main page, starting with B::. To complete the operations, input commands such as system reset, system settings, BSDL file loading, and boundary scan test.



To download TRACE32, see Figure 5.

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3.2 Hardware environment

μTrace for Cortex-M consists of:

- · Universal debugger
- · Debug cable

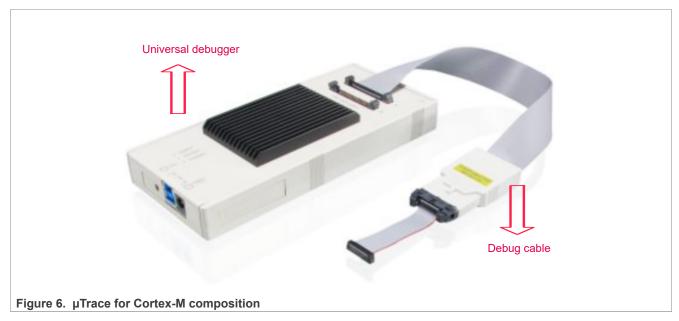
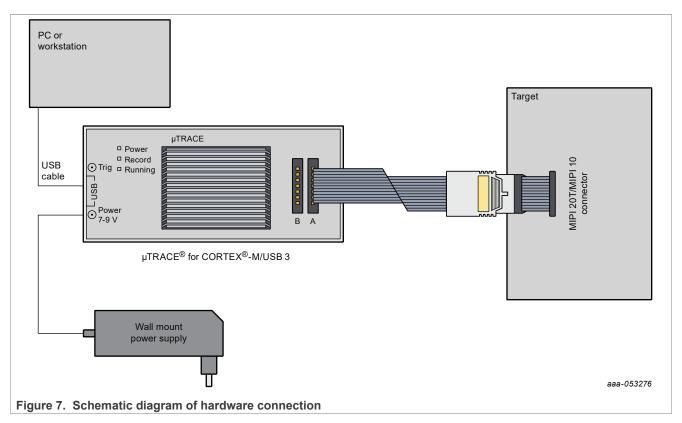


Figure 6 shows the schematic diagram for hardware connection of the entire boundary scan system.

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Below lists the suggestions for users:

- To prevent the debugger or target board being damaged, do not plug or unplug the debugger while the target board is powered on. The recommended sequence for powering on or off is as follows:
 - Power on: debugger > target board
 - Power off: target board > debugger
- The debugger interface has pin1. To prevent damages to the debugger or target, double check the direction.

To set up the hardware environment, perform the following steps:

- 1. Connect the μTrace for Cortex-M debugger to your target board with the standard JTAG interface.
- 2. Connect the μTrace for Cortex-M debugger to the personal computer through the USB cable, and then power on the debugger with a 5 V power adapter. Open Device Manager on the personal computer, and the Lauterbach equipment appears in Trace32 Devices, as shown in Figure 8. If not, check the connection.



3. Power-up your target board.

3.3 Enter boundary scan mode

To let MCU series, including LPC55(S)0x, LPC55(S)1x, LPC55(S)2x, and LPC55(S)6x, enter the boundary scan mode, perform the following steps:

- Connect pins P0 2 (TRST) and P0 11 (SWCLK) to POWER, and pin P0 12 (SWDIO) to GND.
- Press and hold the **ISP(PIO0 5)** button (PIO0 5 = 0).
- Press and hold the **RESET** button (Reset = 0).
- Release the **RESET** button (Reset = 1).

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How to Perform Boundary Scan for LPC55(S)xx based on µTrace and Trace32

- Release the **ISP** button (PIO0 5 = 1).
- Disconnect pins P0 2 (TRST) and P0 11 (SWCLK) from POWER, and pin P0 12 (SWDIO) from GND.

The method for LPC55(S)3x to enter boundary scan mode is different from other LPC55(S)xx including 0x, 1x, 2x, and 6x. To make LPC55(S)3x enter boundary scan mode, perform the following steps:

- Apply a **rectangular** signal with a frequency of 1 MHz (greater than or equal to 500 kHz) and a **duty cycle** of **50** % to P0 3 (**TCK**), which can be provided by a signal generator.
- Connect pins P0 2 (TRST) and P0 4 (TMS) to POWER.
- Hold the RESET pin low for more than 5.5 uS, and then release the RESET pin high.
- Remove the rectangular signal from P0_3 (TCK). This step is crucial.

<u>Figure 9</u> and <u>Figure 10</u> show the timing of LPC553x entering boundary scan. As shown in <u>Figure 9</u>, the duration of the **RESET negative pulse** is **181 ms**, which satisfies the condition of **greater than 5.5 us**. As shown in <u>Figure 10</u>, the frequency of **TCK** is **1 MHz**, which satisfies the condition of **greater than 500 kHz**.

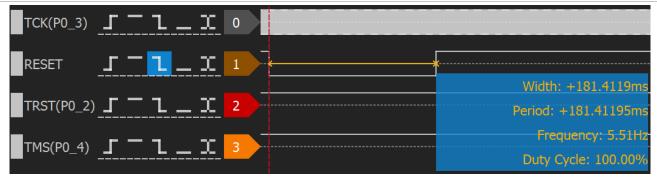
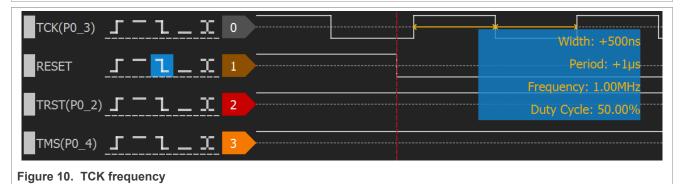


Figure 9. Duration of RESET negative pulse



After the above sequence to enter the boundary scan mode is executed, use a hardware debugger such as Jlink to check the byte addressed at 0×50020004 to determine whether the LPC55(S)xx actually enters the boundary scan mode or not. If the byte addressed at 0×50020004 is 0×07 , it indicates that the chip is already in boundary scan mode. Below takes LPC55S36 as an example to describe this process.

- Use the Jlink debugger to connect the SWD port on the LPC55S36 target board to the USB port on the personal computer.
- Open the J-Link Commander. Figure 11 shows the operation interface.

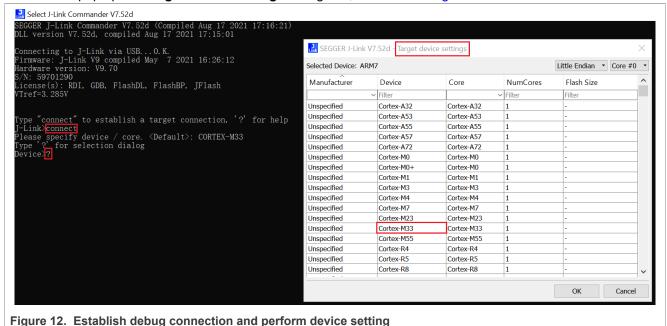
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```
SEGGER J-Link Commander V7.52d (Compiled Aug 17 2021 17:16:21)
DLL version V7.52d, compiled Aug 17 2021 17:15:01

Connecting to J-Link via USB...0.K.
Firmware: J-Link V9 compiled May 7 2021 16:26:12
Hardware version: V9.70
S/N: 59701290
License(s): RDI, GDB, FlashDL, FlashBP, JFlash
VTref=3.288V

Type "connect" to establish a target connection, '?' for help
J-Link>__
Figure 11. J-Link commander
```

- Enter connect to establish a connection between J-Link Commander and LPC55S36.
- Enter ? to pop up the Target device settings dialog box, as shown in Figure 12. Select Cortex-M33.



rigure 12. Establish debug connection and perform device setting

• Select the debug interface. In this example, it is **SWD**, as shown in Figure 13.

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```
🔜 J-Link Commander V7.52d
               Connecting to J-Link via USB...O.K.
              Firmware: J-Link V9 compiled May 7 2021 16:26:12
              Hardware version: V9.70
              S/N: 59701290
              License(s): RDI, GDB, FlashDL, FlashBP, JFlash
              VTref=3.285V
              Type "connect" to establish a target connection, '?' for help J-Link>connect
              Please specify device / core. <Default>: CORTEX-M33
              Type '?' for selection dialog
Device>?
              Please specify target interface:
                J) JTAG (Default)
                S) SWD
                F) FINE
                I) ICSP
                c) c2
                T) cJTAG
               `IF`S.
Figure 13. Specify the target interface as SWD
```

• Specify target interface speed. In this example, use the default value. To continue, press the **enter** button.

```
J-Link Commander V7.52d
             SEGGER J-Link Commander V7.52d (Compiled Aug 17 2021 17:16:21)
             DLL version V7.52d, compiled Aug 17 2021 17:15:01
             Connecting to J-Link via USB...O.K.
Firmware: J-Link V9 compiled May 7 2021 16:26:12
             Hardware version: V9.70
             S/N: 59701290
             License(s): RDI, GDB, FlashDL, FlashBP, JFlash
             VTref=3.280V
             Type "connect" to establish a target connection, '?' for help
             J-Link>connect
             Please specify device / core. <Default>: CORTEX-M33
                      for selection dialog
             Device>
             Please specify target interface:
               J) JTAG (Default)
               S) SWD
               T) cJTAG
             ΓΙF⟩s
             Specify target interface speed [kHz]. <Default>: 4000 kHz
             Speed><mark>_</mark>
                            you can type your desired speed or use
                            default speed by press enter
Figure 14. Specify target interface speed
```

• In the normal mode, check the byte value at address 0x50020004. It is 0x01.

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```
🔜 J-Link Commander V7.52d
        Connecting to target via SWD
Found SW-DP with ID 0x6BA02477
DPIDR: 0x6BA02477
        Scanning AP map to find all available APs
        AP[1]: Stopped AP scan as end of AP map has been reached
        AP[0]: AHB-AP (IDR: 0x84770001)
        Iterating through AP map to find AHB-AP to use
        AP[0]: Core found
AP[0]: AHB-AP ROM base: 0xE00FE000
        CPUID register: 0x410FD214. Implementer code: 0x41 (ARM)
        Feature set: Mainline
        Found Cortex-M33 r0p4, Little endian.
        FPUnit: 8 code (BP) slots and 0 literal slots
        Security extension: not implemented
        CoreSight components:

ROMTbl[0] @ E00FE000

ROMTbl[0]: E00FF000, CID: B105100D, PID: 000BB4C9 ROM Table

ROMTbl[1] @ E00FF000

ROMTbl[1] [0]: E000E000, CID: B105900D, PID: 000BBD21 Cortex-M33
        ROMIDI[1][0]: E000E000, CID: B105900D, PID: 000BBD21 COTTEX-M33
ROMTD1[1][1]: E0001000, CID: B105900D, PID: 000BBD21 DWT
ROMTD1[1][2]: E0002000, CID: B105900D, PID: 000BBD21 FPB
ROMTD1[1][3]: E00000000, CID: B105900D, PID: 000BBD21 ITM
ROMTD1[1][5]: E0041000, CID: B105900D, PID: 000BBD21 ETM
ROMTD1[1][6]: E0042000, CID: B105900D, PID: 000BBD21 CSS600-CTI
ROMTD1[0][1]: E0040000, CID: B105900D, PID: 000BBD21 Cortex-M33
Cortex-M33 identified.

Lating many 0x50022004
        I-Link mem8 0x50020004 1
         50020004 = 01
          -Link>_
                                 In normal mode, byte value at address 0x50020004 is 0x01
Figure 15. Check byte value at address 0x50020004 in normal mode
```

• Let LPC55S36 enter boundary scan mode and check the byte value at address 0x50020004. Now, in boundary scan mode, it is 0x07.

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```
J-Link Commander V7.52d
 Connecting to target via SWD
Found SW-DP with ID 0x6BA02477
 DPIDR: 0x6BA02477
 AP map detection skipped. Manually configured AP map found. AP[0]: AHB-AP (IDR: Not set)
AP[0]: Core found
AP[0]: AHB-AP ROM base: 0xE00FE000
 CPUID register: 0x410FD214. Implementer code: 0x41 (ARM)
 Feature set: Mainline
 Found Cortex-M33 r0p4, Little endian.
 FPUnit: 8 code (BP) slots and 0 literal slots
Security extension: not implemented
 CoreSight components:
ROMTb1[0] @ E00FE000
 ROMTb1[0][0]: E00FF000, CID: B105100D, PID: 000BB4C9 ROM Table
 ROMTb1[1] @ E00FF000
ROMTb1[1] @ E00FF000

ROMTb1[1][0]: E000E000, CID: B105900D, PID: 000BBD21 Cortex-M33

ROMTb1[1][1]: E0001000, CID: B105900D, PID: 000BBD21 DWT

ROMTb1[1][2]: E0002000, CID: B105900D, PID: 000BBD21 FPB

ROMTb1[1][3]: E0000000, CID: B105900D, PID: 000BBD21 ITM

ROMTb1[1][5]: E0041000, CID: B105900D, PID: 002BBD21 ETM

ROMTb1[1][6]: E0042000, CID: B105900D, PID: 000BBD21 CSS600-CTI

ROMTb1[0][1]: E0040000, CID: B105900D, PID: 000BBD21 Cortex-M33
  Cortex-M33 identified.
 J-Link>mem8 0x50020004 1
50020004 = 07
  [-Link>_
                             In boundary scan mode, byte value at address 0x50020004 is 0x07
Figure 16. Check byte value at address 0x50020004 in boundary scan mode
```

4 Interactive boundary scan test

To perform a boundary scan test using μ Trace for Cortex-M debugger and TRACE32 software, follow the steps below:

1. Open the TRACE32 software and choose ARM32 USB.

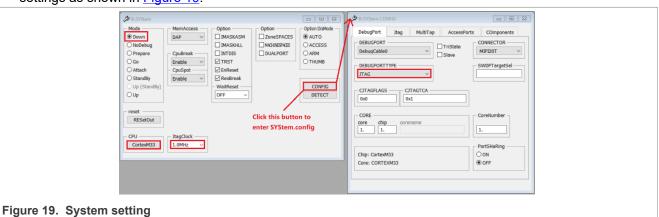
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2. <u>Figure 18</u> shows the main page of TRACE32 for ARM32. If the status bar at the bottom of the main page shows **power down** instead of **system down**, check the power supply of the debugger and the connection with the JTAG interface of the target board.



3. Click **CPU** -> **System Settings...** in the menu bar, and the system setting dialog appears. Perform system settings as shown in <u>Figure 19</u>.

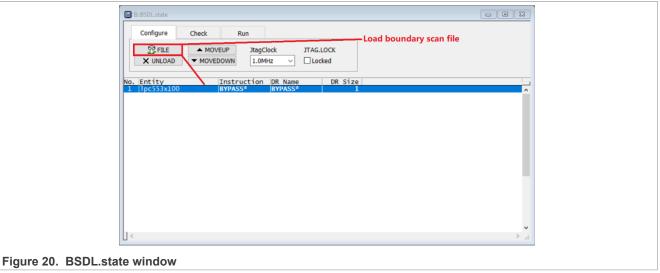


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4. Type in below commands, with each command followed by entering:

```
BSDL.RESet
BSDL.ParkState Select-DR-Scan
BSDL.state
```

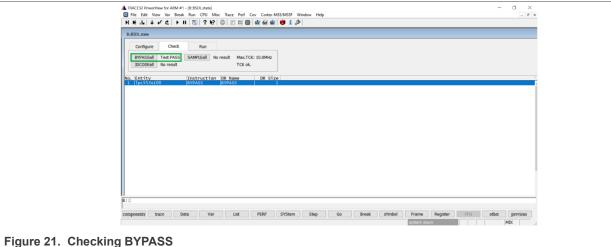
5. The **BSDL.state** window appears, as shown in <u>Figure 20</u>. Click the **FILE** button and load the BSDL file you want to validate.



6. After loading the file, type in command as below:

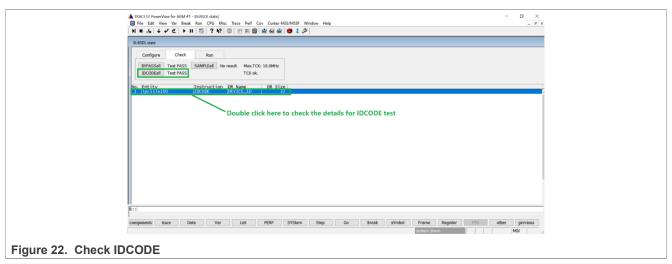
BSDL.SOFTRESET

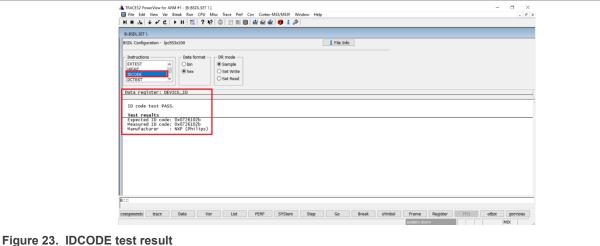
7. Switch to the **Check** tab of the **BSDL.state** window. To see whether both results can pass, click **BYPASSall** and **IDCODEall**, as shown in <u>Figure 21</u> and <u>Figure 22</u>. Double-click the entity name in <u>Figure 22</u>, and the IDCODE test result can be seen in the **BSDL.SET** window, as shown in <u>Figure 23</u>.



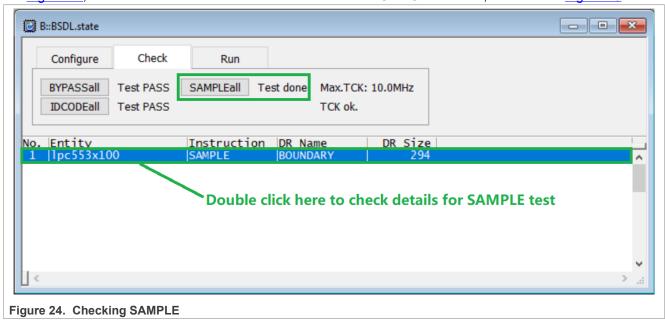
rigure 21. Checking BTFA33

How to Perform Boundary Scan for LPC55(S)xx based on µTrace and Trace32

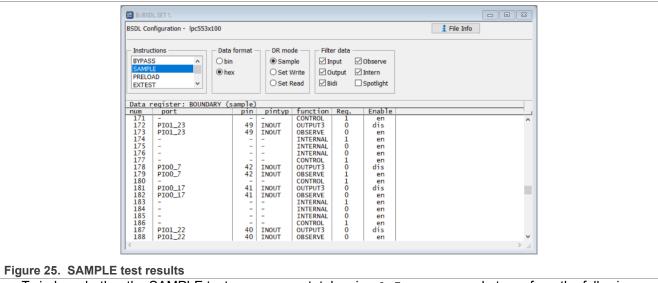




8. Click the **SAMPLEall** button, and **No result** becomes **Test done**. Double-click the entity name, as shown in <u>Figure 24</u>, and the SAMPLE test result can be seen in the **BSDL.SET** window, as shown in <u>Figure 25</u>.

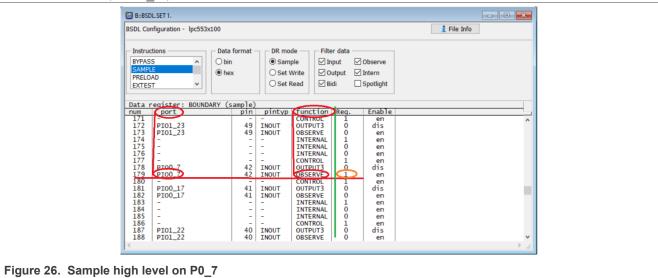


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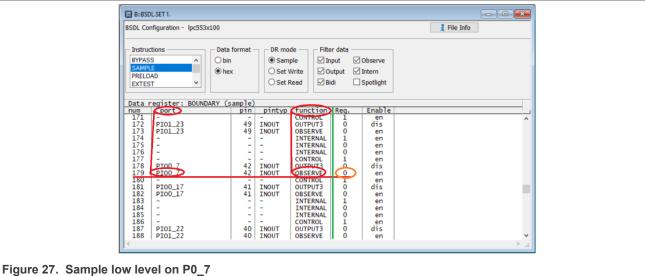


To judge whether the SAMPLE test passes or not, take pin $P0_7$ as an example to perform the following steps:

- a. Apply high level to this pin. Use the BSDL.RUN command to run the **SAMPLE** test. Search the line where the port is PIOO_7 and function is **OBSERVE**. Read the register value in the **Reg.** column and it is **1**, as shown in Figure 26.
- b. Apply a low level to this pin. Check the sample result and it is **0**, as shown in <u>Figure 27</u>. Therefore, the pin P0 7 passes SAMPLE test.



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Use the above method to traverse all the IO pins defined in the BSDL file. If all the IO pins pass the test, the SAMPLE test of BSDL passes.

9. Enter the BSDL. SET command on the TRACE32 command line, and the BSDL.SET window appears. In the Instructions field, click EXTEST and in the DR mode field, choose Set Write, as shown in Figure 28.

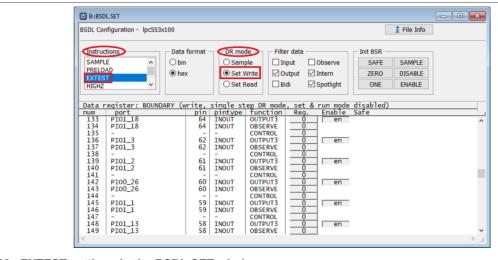


Figure 28. EXTEST settings in the BSDL.SET window

Switch to the BSDL.state window and check SetAndRun and TwoStepDR, as shown in Figure 29.

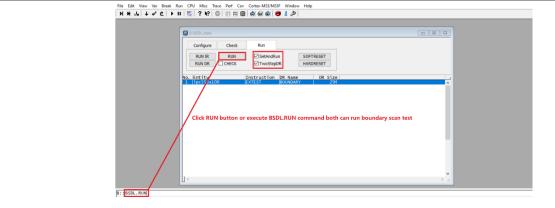


Figure 29. EXTEST settings in BSDL.state window

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Switch back to the **BSDL.SET** window. Taking the pin $P0_7$ as an example to describe how to perform **EXTTEST**. Enable output of the pin $P0_7$ by clicking the button in the **Enable** column. Toggle the output logic state 0 or 1 of this pin by clicking the button in the **Reg.** column, as shown in <u>Figure 30</u>. Use a multimeter to measure whether the logic state really toggles on this pin.

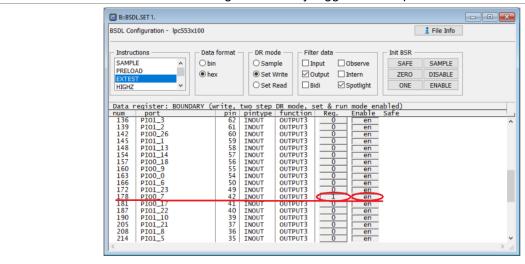


Figure 30. Enabling and toggling signal level

Use the above method to traverse all the IO pins defined in the BSDL file. If all the IO pins pass the test, the EXTTEST test of BSDL passes.

10. Use **PRELOAD** test with **EXTTEST**. To enable and preset driving buffers to 1 or 0 of all IO pins, click **ONE** or **ZERO** and then **ENABLE** in the **Init BSR** field, as shown in <u>Figure 31</u>.

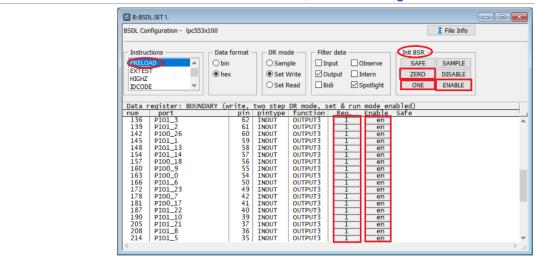


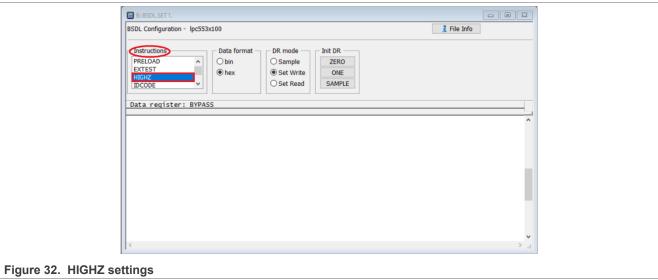
Figure 31. Preload IO output status

Run the **PRELOAD** test and then **EXTTEST**. Use a multimeter to measure whether the logic state of all IO pins matches the preload values.

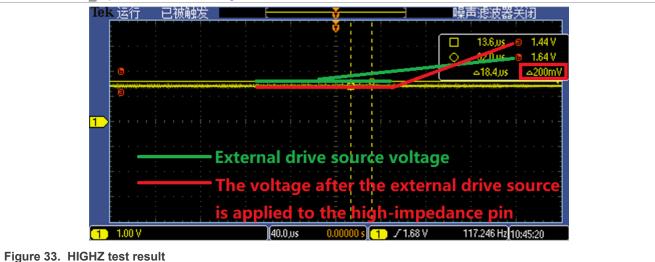
Use the above method to traverse all the IO pins defined in the BSDL file. If all the IO pins pass the test, the PRELOAD test of BSDL passes.

11. Choose **HIGHZ** in the **Instructions** field in the **BSDL.SET** window and then run the **HIGHZ** test. All IO pins defined in the BSDL file are in the high-impedance state. Taking 3.3 V logic as an example, if an intermediate level, such as 1.65 V, is applied to a pin in a high-impedance state, use a multimeter to measure the pin. The measurement is 1.65 V and the pin in the high-impedance state is regarded as an open circuit due to its high impedance. It does not cause a significant voltage drop to the external driving source.

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After the **HIGHZ** test starts, all pins are in a high impedance state. Then select a pin and apply an intermediate level. Taking 1.64 V as is selected, use a multimeter to measure the pin level. The **HIGHZ** test result of P0 7 pin is as shown in Figure 33.



As shown in <u>Figure 33</u>, when the external driving source is applied to the pin P0_7, it only causes a 200 mV voltage drop. P0_7 is indeed in a high impedance state.

Use the above method to traverse all the IO pins defined in the BSDL file. If all the IO pins pass the test, the **HIGHZ** test of BSDL passes.

5 Let LPC55(S)xx pass boundary scan SAMPLE test

After LPC55(S)xx is reset, the digital input function of some pins is disabled. If the SAMPLE test is directly performed on these pins, these pins do not pass the test.

For LPC55(S)xx, the DIGIMODE bit of the IOCON register controls the digital input function, as shown Figure 34.

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```
Select Digital mode
                         0 - Disable digital mode. Digital input set to 0.
         DIGIMODE

    Enable Digital mode. Digital input is enabled.

Figure 34. DIGIMODE bit in IOCON register
```

Take LPC55(S)3x as an example to describe how to enable the digital input function of the pin P0 1 when the chip is in boundary scan mode. The setting methods of other pins are similar. The detailed steps are described as follows:

- 1. Open Jlink commander.
- 2. For LPC55(S)3x, the clock enable the bit of IOCON is bit 13 in the AHBCLKCTRLO register with address 0x40000200. If this bit is set to 1, the clock for IOCON is enabled.

```
check whether chip is in boundary scan mode or not. If the byte value command. '?' for nelp. addressing at 0x50020004 is 0x07, chip is in boundary scan mode
    own command. '?' for help.

ok>mem32 0x40000200 1 Read the default value of the AHBCLKCTRLO register after reset, it is
nknown command. 7 101 ne
-Link>mem32 0x40000200 1
0000200 = 000001FB
     wn command. '?' for help.
Link>w4 0x40000200 0x21FB
iting 000021FB -> 40000200
       command. '?' for help.
Link>mem32 0x40000200 1 Check if the above setting is valid
```

Figure 35. Enabling IOCON clock

3. The address of the IOCON register corresponding to the PO 1 pin is 0x40001004. To enable the digital input function, set bit 8 (DIGIMODE) of this register to 1. To set the pin as floating input, pulldown input, and pullup input, set the bit field [4:5] to 0x00, 0x01, and 0x02 as required.

```
J-Link>mem32 0x40001004 1
40001004 = 00000000
                                   Read the reset value of the IOCON register corresponding to pin P0 1, it is 0)
 J-LINK/
Inknown command. '?' for help.
 J-Link>w4 0x40001004 0x120
Vriting 00000120 -> 40001004
                                        et P0_1 as digital pull-up input
 J-Link/
Jnknown command. '?' for help.
 J-Link>mem32 0x40001004 1
40001004 = 00000120 ch
Figure 36. Setting P0_1 pin as digital pull-up input
```

Automated boundary scan test

Through the above introduction to the interactive boundary scan test, some interactive testing steps are not conducive for quick test. To improve test efficiency, TRACE32 supports a practice script. To perform an automated boundary scan test, write the script program.

On the main page of TRACE32, the File menu provides three submenu items related to script, New Script, Open Script..., and Run Script.... They are used to create, open, and run script.

A script example used to automate the boundary scan test is described as below.

```
;System setup
SYStem.Mode Down
                                  ; Disables the debug mode.
SYStem.CPU CortexM33
                                  ;Tells TRACE32 the exact CPU type
                                  ;used on your target, CPU core of
```

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```
;LPC553x is Cortex-M33.
SYStem.CONFIG.DEBUGPORTTYPE JTAG ; Specifies which probe cable shall
                                 ; be used, here, JTAG is selected
                                  ; Selects JTAG frequency (TCK)
SYStem.JtagClock
                    1MHz
;BSDL Settings
BSDL.RESet
                                 ; Initialize the boundary scan engine
BSDL.ParkState Select-DR-Scan
                                 ;Set PartState as Select-DR-Scan
                                  ; Open BSDL.state window
BSDL.state
;Configure boundary scan chain
BSDL.FILE lpc553x100.bsdl
                                 ; your BSDL file name
;Check boundary scan chain
BSDL.SOFTRESET
IF !BSDL.CHECK.BYPASS()
                                 ;BYPASS Test
  BSDL.BYPASSall
  PRINT %ERROR "Bypass test failed"
  ENDDO
IF !BSDL.CHECK.IDCODE()
                                ;IDCODE Test
 BSDL.IDCODEall
 PRINT %ERROR "ID code test failed"
 ENDDO
;Perform SAMPLE test
BSDL.SAMPLEall
:Perform EXTTEST
;Pin output settings, you can add other pin output settings
BSDL.SET 1. PORT PIO0 7 0
                                 ;Set PIO0 7 output as 0
BSDL.RUN DR
                                 ;Only apply data register settings
                                 ;to the boundary scan chain
BSDL.SET 1. IR EXTEST
                                 ;Only apply instruction register
                                 ; settings to the boundary scan chain
BSDL.RUN
                                 ;BSDL run
;Perform HIGHZ test
BSDL.SET 1. IR HIGHZ
                                 ;Only apply instruction register
                                 ; settings to the boundary scan chain
BSDL.RUN
                                 ;BSDL run
```

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8 Revision history

Table 4 summarizes the revisions to this document.

Table 4. Revision history

Revision number	Release date	Description
1	14 November 2023	Updated images to svg format Updated <u>Section 3.2</u>
0	07 January 2022	Initial public release

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